

# 3D Compton Imaging of Distributed Sources Around the Chernobyl NPP

Nuclear Science & Security Consortium

## Introduction

The detection, characterization, localization, and mapping of gamma-ray source distributions in real-world environments is useful for many applications including safeguards, emergency response, and nuclear contamination remediation. Traditionally, radiation mapping is performed with hand monitoring or a series of 2D static measurements, but portable detection systems with contextual sensors have been developed which can allow for free-moving 3D gamma-ray imaging in a method called scene data fusion (SDF) [1].

## **3D Compton Imaging**

### Compton imaging is a gamma-ray imaging modality based on Compton scattering

- Double interaction events a Compton scatter followed by a photoelectric absorption
- To localize 137Cs, use events that deposit 662 keV in the detector across its two interactions.
- Compton cones are defined by a scatter axis given interaction positions and cone opening angle using Compton kinematics.

## 2D Compton

- 3D positions of 1<sup>st</sup> two interactions
- Energy deposited in each interaction



Fig. 1: Compton cone generated from double interaction events Free-moving 3D Compton • Everything from 3D Compton • Real time solution of position and orientation during each gamma-ray event Handle Lidar Camera

LAMP Box

## 3D Compton

 Everything for 2D Compton Position and orientation at each measurement to

## **Polaris-LAMP and Scene Data Fusion**

Polaris-LAMP is the commercially available Polaris-H quad detector fitted with LBNL's LAMP package

- **Polaris-H:** pixelated CdZnTe detector developed as a 2D static imager [2].
- LAMP package: onboard computer, LiDAR unit, visual camera, inertial measurement unit (IMU), and a GPS module [3]
- Simultaneous Localization and Mapping (SLAM): continuously updates a map of surroundings and estimates pose as the detector moves through the scene [4].



Fig. 3: SDF demonstrated with a <sup>137</sup>Cs point source in a laboratory setting. Reconstruction on 662 +/- 10 keV gammas with 546 Compton cones



- Scene Data Fusion (SDF) is a method of equipping portable radiation detection systems with contextual sensors to allow free-moving 3D
- gamma-ray imaging 3D image reconstruction is constrained to intersections of in the scene





- Compton cones
- properly rotate and translate

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## **Chernobyl Measurement**

Significant contamination remains across the Chernobyl Nuclear Power Plant (CNPP) exclusion zone despite ongoing remediation efforts. The primary contaminant is Cs-137, with a gamma-ray energy of 662 keV.

## To demonstrate its effectiveness in mapping distributed radiation source environments, Polaris-LAMP was brought to:

- Chernobyl Nuclear Power Plant
- Pripyat, the abandoned working town for the plant.
- Slavutych, the nearby town constructed for the CNPP remediation effort.



measurement is colorized by gross counts from the detector.





Fig. 5: Compton reconstruction on the scene, colorized to show weight on a min-max normalized scale. Colorization is suppressed for the bottom 10% of weight. The fountain wells collected contaminated rain and groundwater following the CNPP accident, resulting in high weight

Compton cones with surfaces present

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